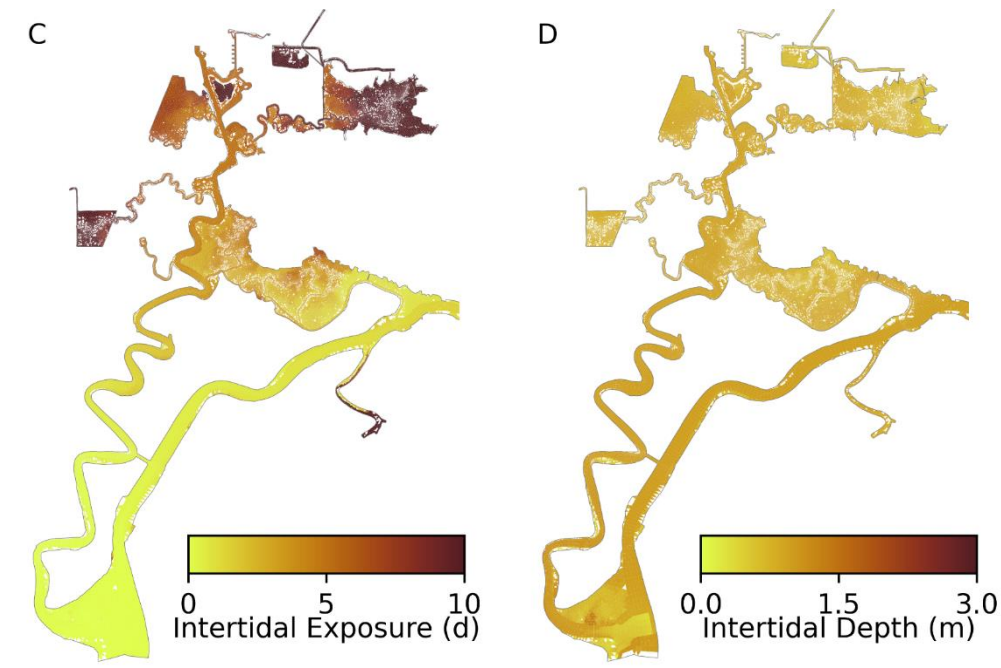
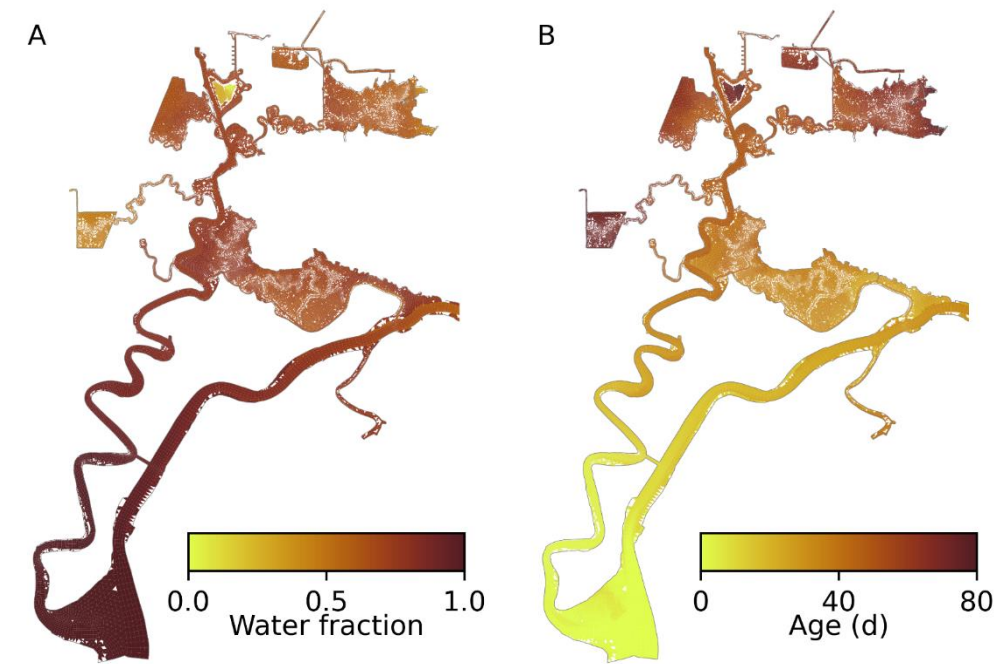


# Tracer-Based Phytoplankton Modeling

Hugo B. Fischer Award Acceptance Presentation

Edward Gross

September 23, 2024



# Thank You Mentors!

- Jeffrey Koseff, Stephen Monismith
- Ralph Cheng, Jon Burau
- Vincenzo Casulli, Guus Stelling
- Wim Kimmerer, John DeGeorge, Richard Rachiele



# Thank You RMA Team and Other Colleagues!

- Rusty Holleman – Modeling guidance and python scripts
- Richard Rachiele, Stacie Grinbergs – Modeling approach and inputs
- Steve Andrews – UnTRIM interface and application
- Benjamin Saenz – Python scripts and model inputs
- John DeGeorge – Business development and project management
- Scott Burdick – Hydrodynamic grid and model setup
- Michael MacWilliams, David Ralston, Gerard Ketefian, Nick Nidzieko





# Questions for Suisun Marsh Phytoplankton Modeling

- Which regions of Suisun Marsh are most productive?
- What are the mortality rates?
  - Clam grazing
  - Zooplankton grazing or other mortality



*Article*

## Using Age Tracers to Estimate Ecological Rates in a Phytoplankton Model

Edward Gross <sup>1,2,\*</sup>, Rusty Holleman <sup>3</sup>, Wim Kimmerer <sup>4</sup>, Sophie Munger <sup>3</sup>, Scott Burdick <sup>1</sup> and John Durand <sup>3,5</sup>

# Ecological Modeling Approaches

## Option 1: Box model

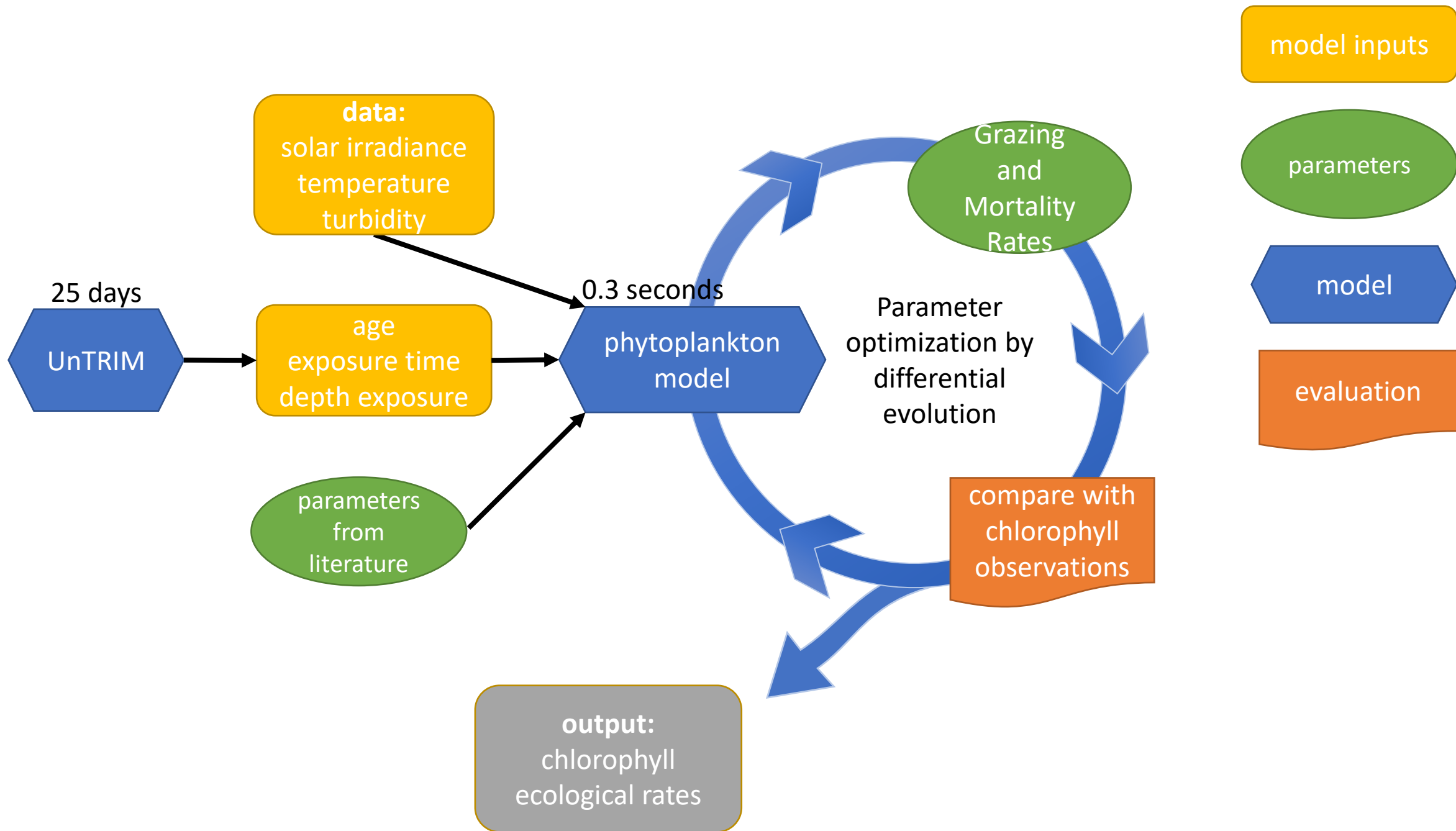
- Fast, simple
- Ignore or drastically simplify transport

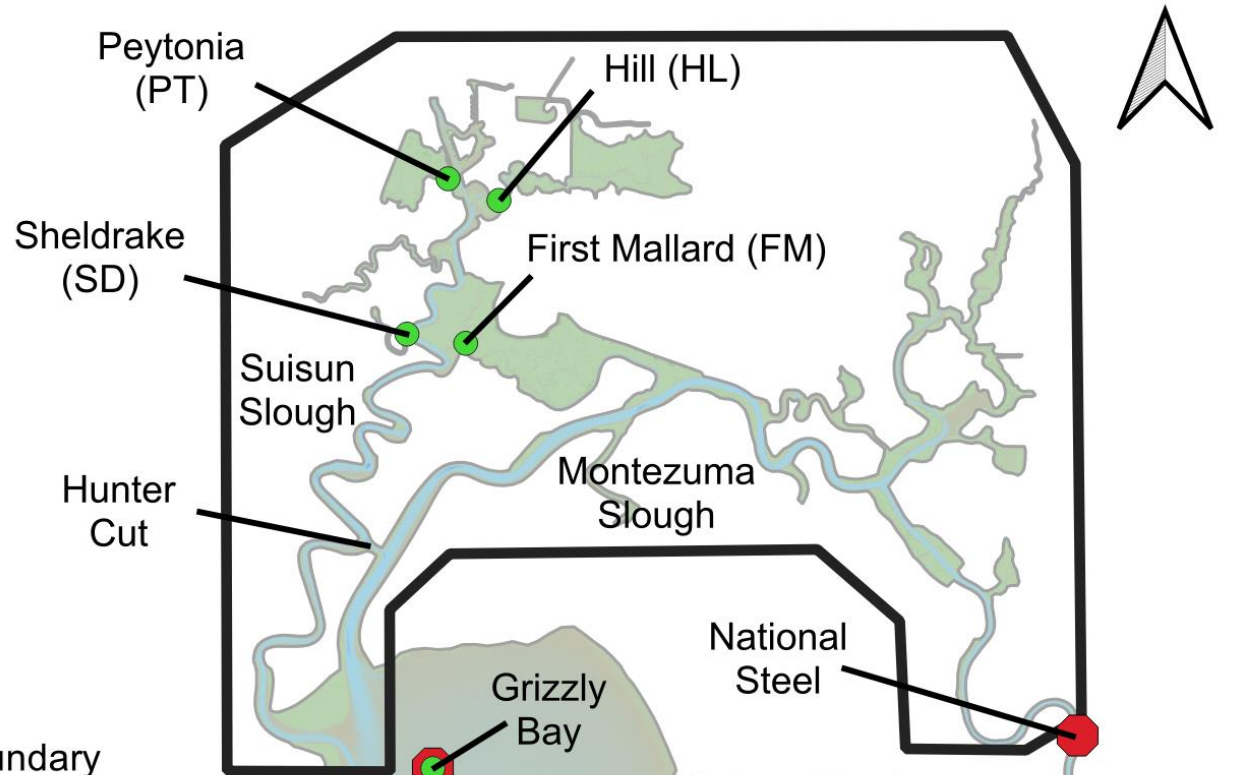
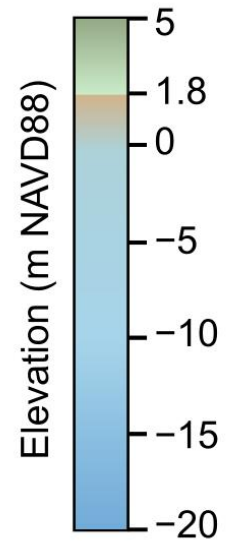
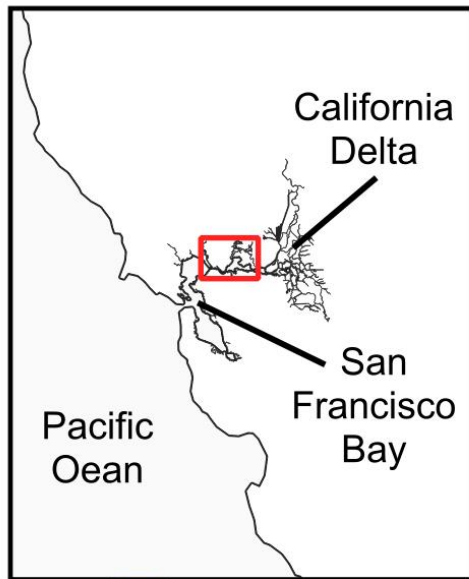
## Option 2: Coupled hydrodynamics and ecology

- Transport affects transformation
- Slow

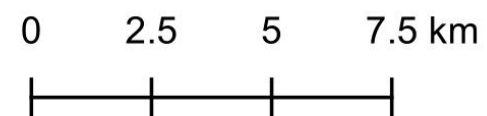
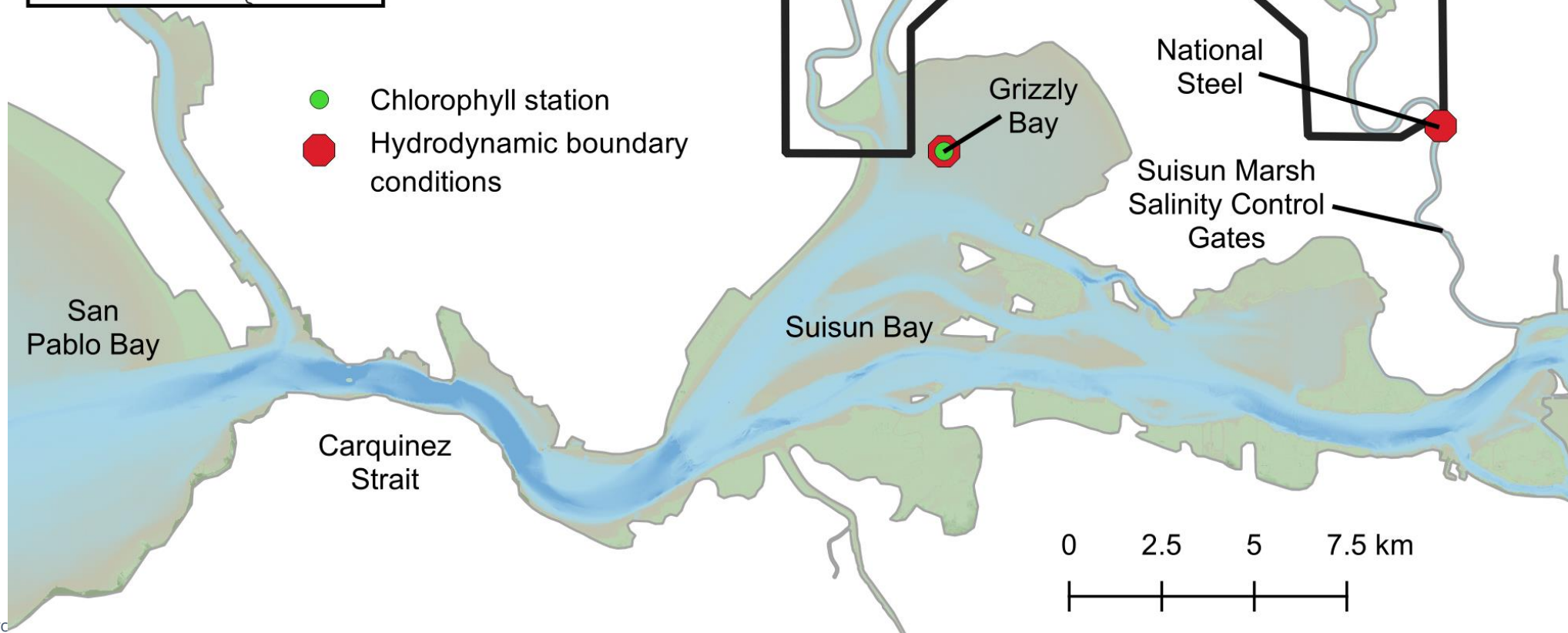
## Option 3: Lagrangian model utilizing water age tracers

A box model where “the box is moved around by the hydrodynamics.”

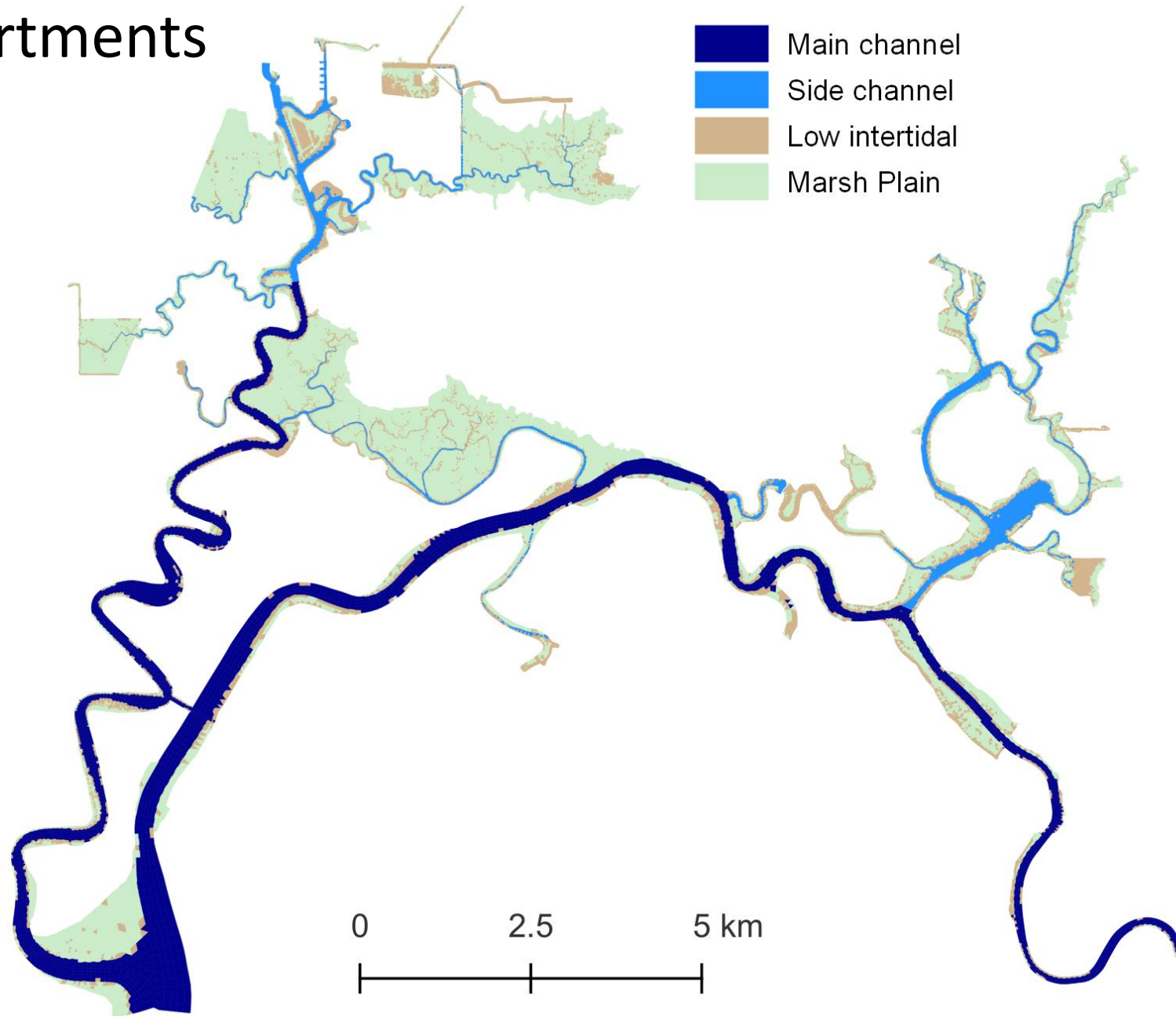




- Chlorophyll station
- Hydrodynamic boundary conditions

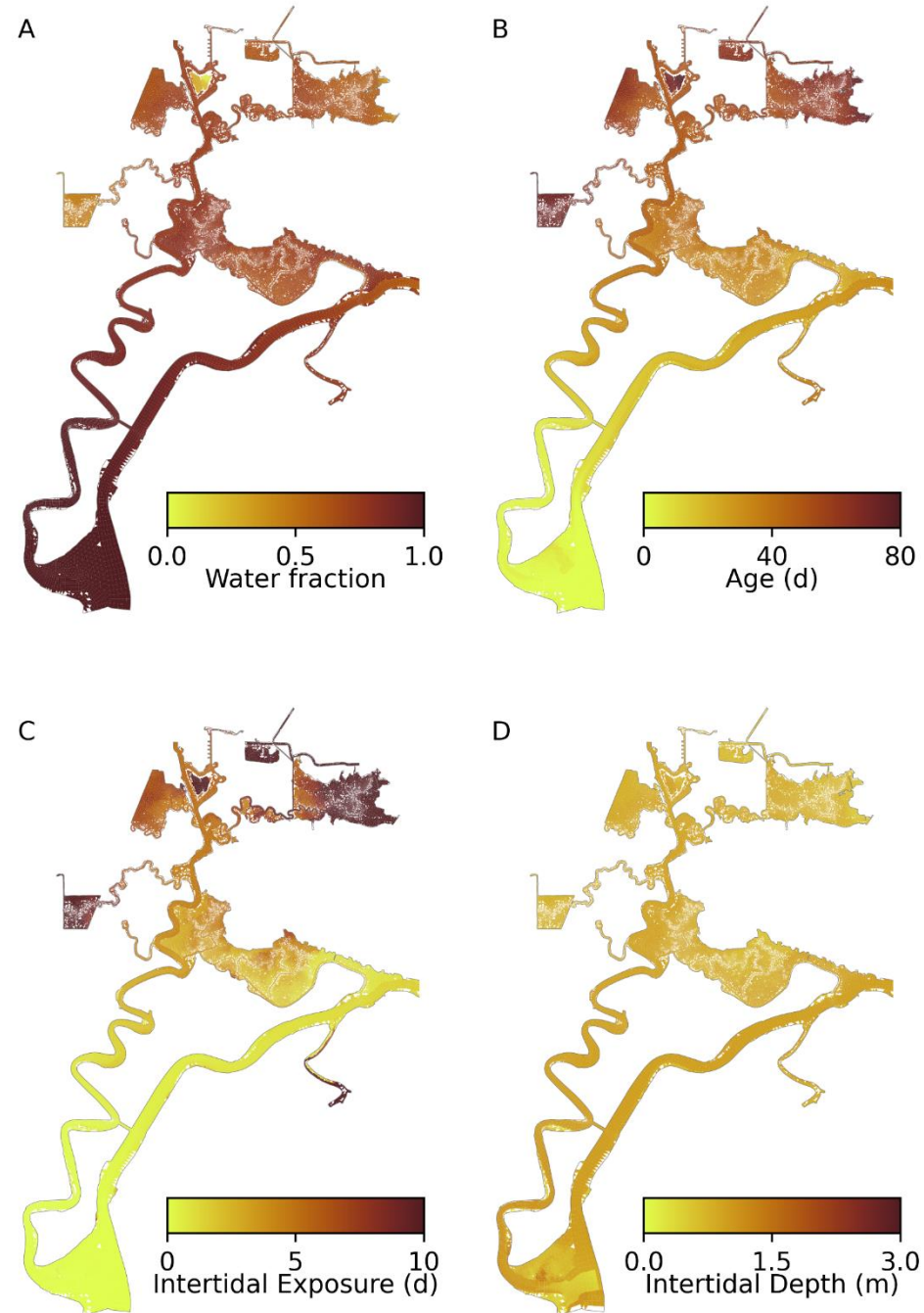


# Spatial Compartments





# Example Snapshots of Predicted Tracer Distributions

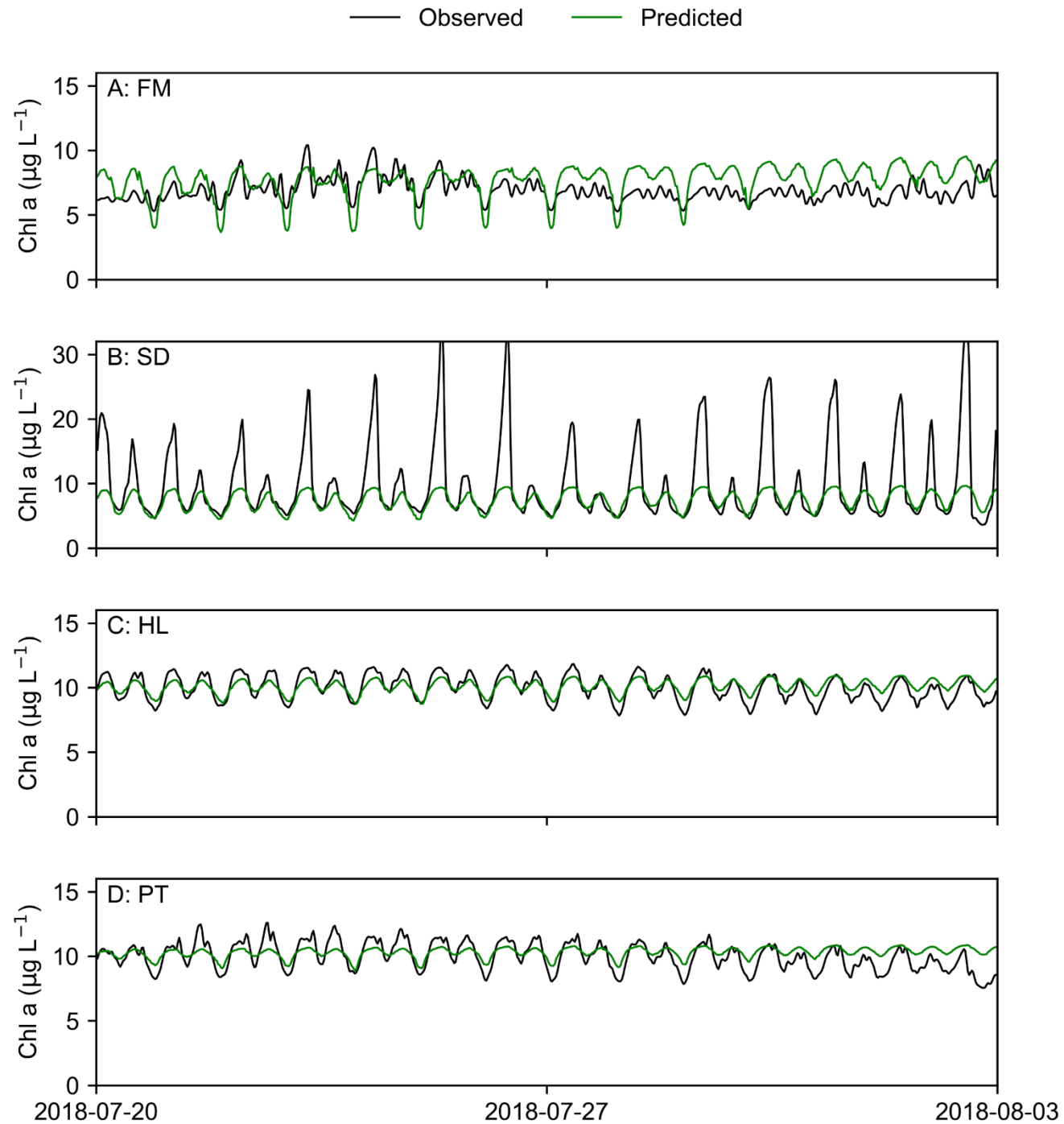
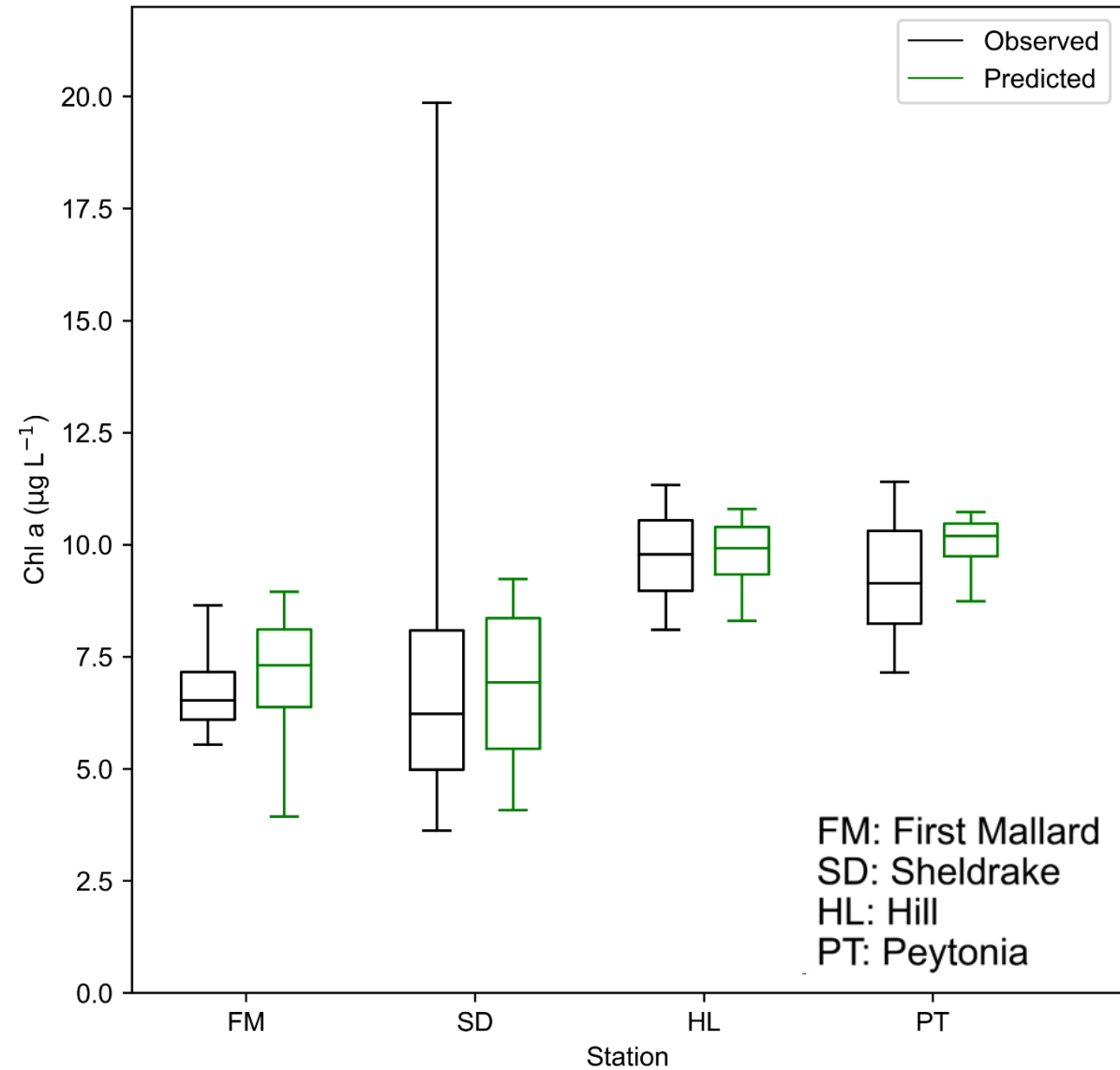


# Water Age Tracer-Based Phytoplankton Model

- Light limited production equations from Cloern (2007)
- Losses (*unknown parameters in green*)
  - $\mu_{loss} = PM + ZG + \frac{CG}{H}$ 
    - **PM** is phytoplankton mortality rate (d<sup>-1</sup>)
    - **ZG** is microzooplankton grazing rate (d<sup>-1</sup>)
      - $ZG = \max(0, -0.3 + 0.93 * \mu_{growth})$  (Kimmerer and Thompson 2014)
    - **CG** is clam grazing rate (m d<sup>-1</sup>)
- **Analytical** solution for chlorophyll concentration (Wang et al. 2019)

- $$P(a) = \frac{P_{in}(t-a)e^{\overline{\mu_{net}} a}}{1+k_p P_{in}(t-a)(1-e^{\overline{\mu_{net}} a})}$$

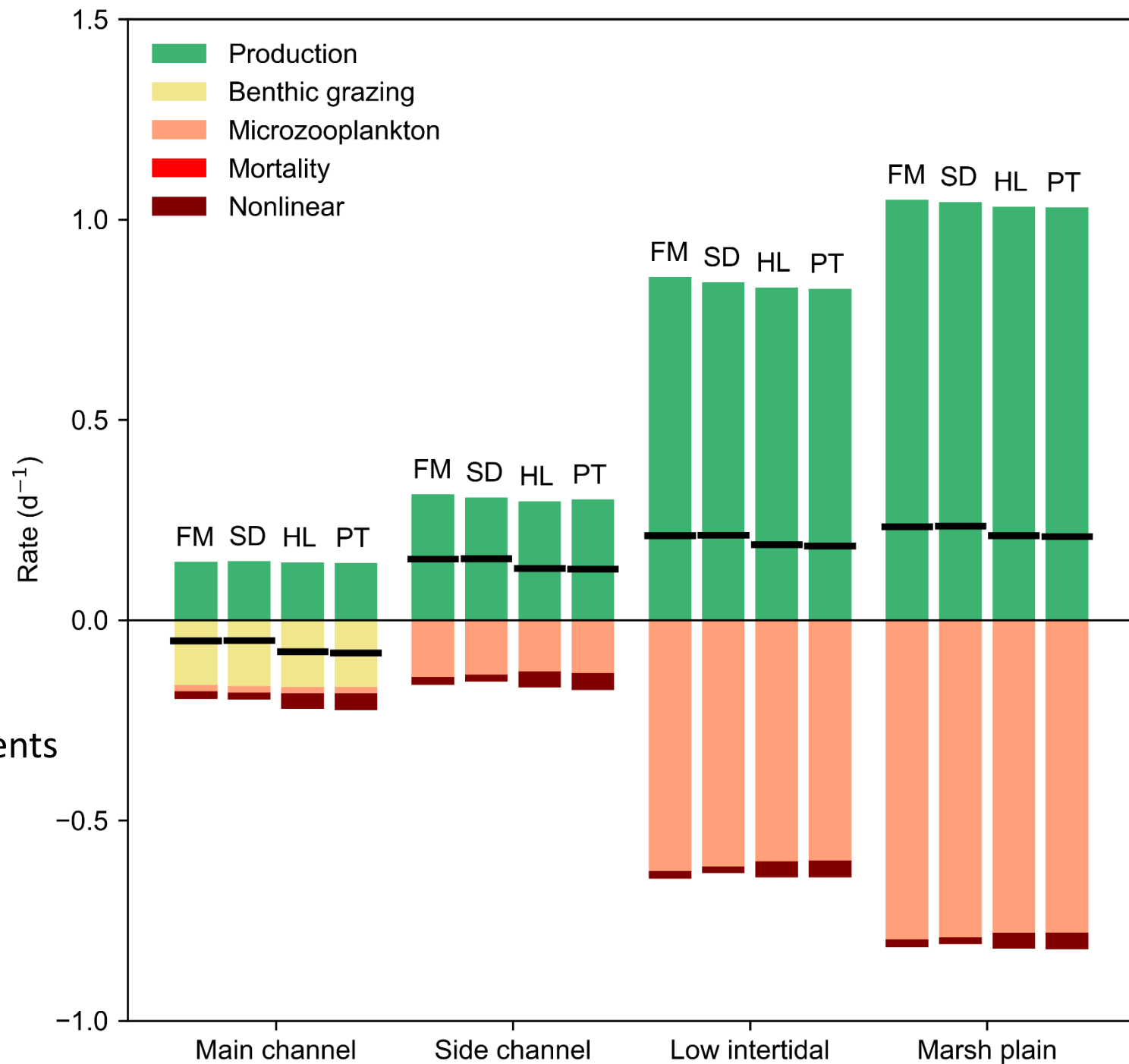
# Calibration



# Best-Fit Parameters

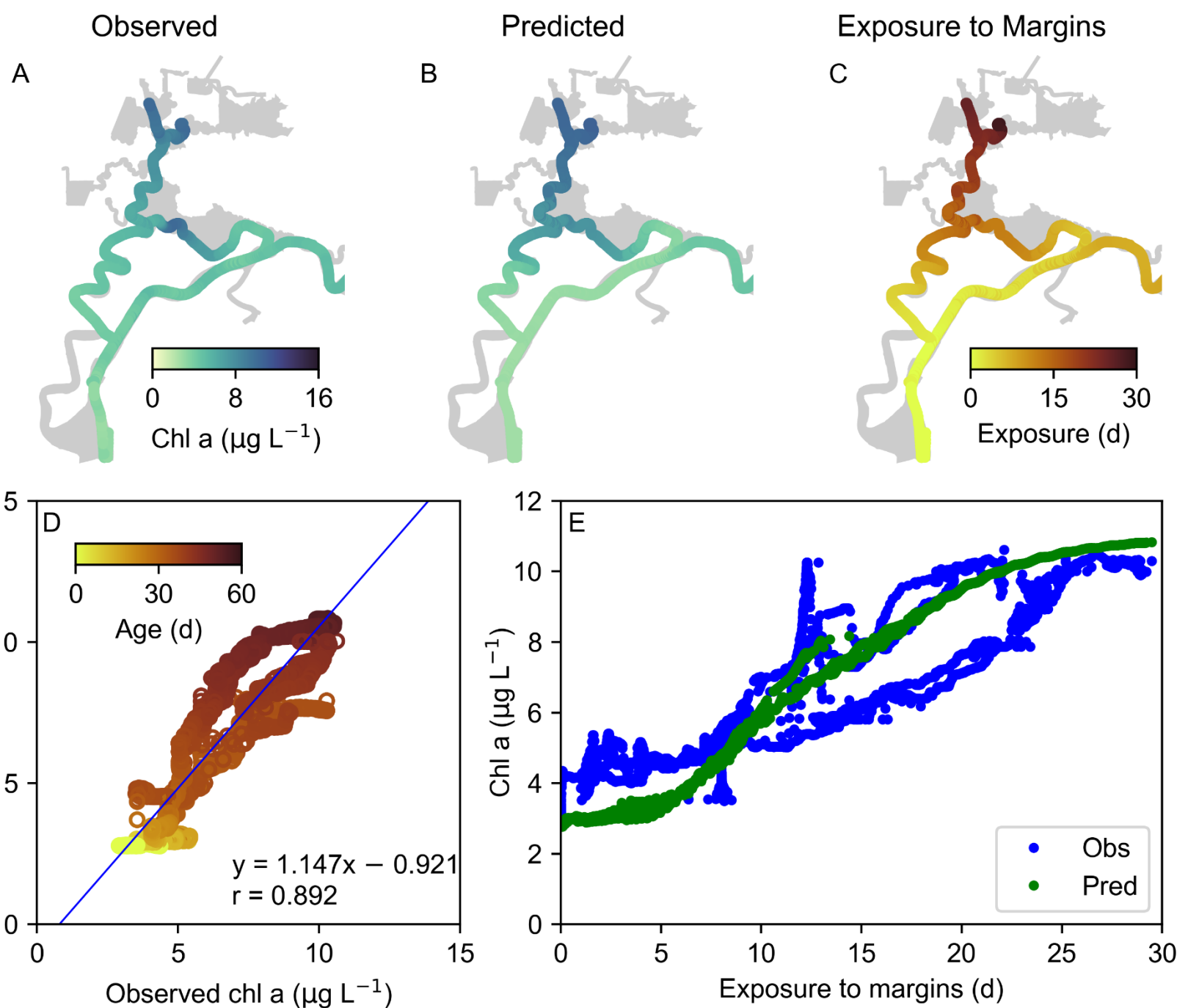
Parameter	Best Fit Value
Main channel grazing	1.13 m d <sup>-1</sup>
Side channel grazing	0 m d <sup>-1</sup>
Nonlinear feedback	-0.091 L μg <sup>-1</sup>
Mortality	0.0 d <sup>-1</sup>

- Net loss in main channel
- Net production in other spatial compartments
- Only non-zero estimated grazing rate is in main channel



# Validation

High-speed mapping data from USGS:  
Bergamaschi et al. 2021  
<https://www.usgs.gov/data/spatial-assessment/nutrients-and-water-quality/constituents-suisun-marsh-salinity-control-gate>





# Conclusions

- The strength of this type modeling approach is to quickly:
  - Test model formulations
  - Fit unknown rates or other parameters to data
  - Gain conceptual understanding
- Derived rates can be used in a more complex ecological model
- Difficulties to applying at larger spatial and temporal scales
  - Spatial and temporal variability in parameters
  - Multiple sources of water



*Technical Note*

## Estimating Effective Light Exposure by Property-Tracking Tracers

Edward Gross <sup>1,2,\*</sup>, Rusty Holleman <sup>1</sup>, Eric Deleersnijder <sup>3</sup>  and Eric J. M. Delhez <sup>4</sup> 

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